



4WRKE...type Electro-Hydraulic Proportional Directional Valve



4WRKE...3XJ type

Size 10, 16, 25, 32

Max. Working Pressure: 315 bar

Max. Flow: 1600 L/min

Contents		Features
Function and configuration Symbols Ordering code Technical data Electrical connections Characteristic curves Unit dimensions	02 03 03 04 05 06-08 09-12	 Pilot operated 2-stage proportional directional valve Valve for the control of the size and direction of a flow For subplate mounting, porting pattern to DIN 24 340 form A Spring centred main spool
		 Integrated control electronics

Function and configuration

Proportional directional valve type 4WRKE...3XJ...

4WRKE type valve is a 2-stage proportional directional control valves. They control the size and direction of a flow. The main stage is closed loop position controlled so that the spool position is also independent of flow forces at larger flows.

The valve consists of the pilot control valve(1), housing (8), main spool (7), covers (5 and 6), centering spring (4), inductive position transducer (9) and the pressure reducing valve (3).

If no input signal is being applied then the main spool (7) is held in the centere position by the centering spring (4). The two control chambers in the covers (5 and 6) are connected via the valve spool (2) to tank. The main spool (7) is connected to suitable control electronics via the inductive position transducer(9). The positional change of the main spool (7) as well as the alteration of the command value at the summation point of the amplifier produces a differential voltage.

With the command actual value comparison a possible control deviation is recognised via the electronics and an electrical current is applied to the proportional solenoid of the pilot valve (1).

The current induces, within the solenoid, a force which is passed on to the solenoid pin which in turn actuates the control spool. The flow which is provided via the control cross sections causes the main spool to move.

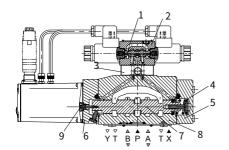
Pilot control valve type 4WRAP 6 W7...-3XJ/G24...

The pilot control valve is a direct operated proportional valve. The control edge geometrics were designed and optimised for the use as a pilot control valve for the proportional directional valves type 4WRKE. The proportional solenoids are pressure tight, oil-immersed DC solenoids with removable coil. They convert an electrical current proportionally into a mechanical force. An increase in the current strength causes an appropriately higher solenoid force.

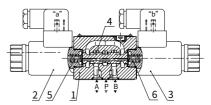
The valve consists of housing(1), proportional solenoids(2 and 3), spool(4) and springs(5 and 6).

In the de-energised condition both actuator ports are connected to tank. If one of the two solenoids (2 or 3) is energised, then the solenoid force moves the valve spool (4) against the spring (6 or 5).

Once the overlap area is overcome, the connection to tank of one of the two actuator ports is blocked and the connection to the pressure chamber is established. There is flow from P to the control chamber of the main stage.

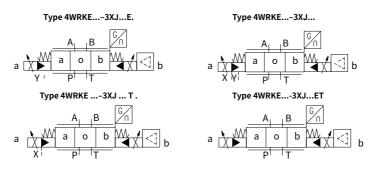


Type 4WRKE 16 ...-3XJ...

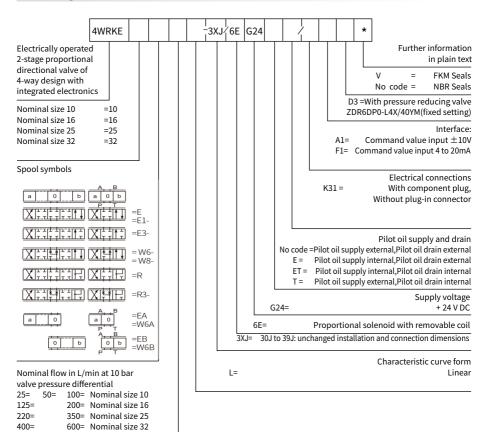


Type 4WRAP 6 W7...-3XJ/G24...

Symbols (simplified)



Ordering code



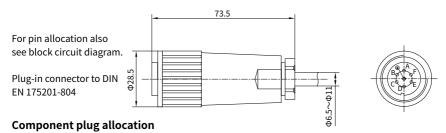
Technical data

General						
Nominal size		10	16	25	32	
Installation and commissioning guidelines		Optional, preferably horizontal				
Storage temperature range	°C	– 20 to + 80				
Ambient temperature range	°C	– 20 to + 50				
Weight	kg	8.7	11.2	16.8	31.5	

Hydraulic (measured at p=100bar,with HLP46 at ϑ_{oit} =40°C \pm 5°C)								
Operating	-Pilot control valve	Pilot oil supply	bar	25 to 315				
pressure	-Main valve	Ports P, A, B	bar	Up to 315	Up to	350	Up to 350	Up to 350
<u> </u>	Port T	Internal	bar	Static < 10				
Return pressure	(Pilot oil drain)	External	bar	Up to 315	Up to	250	Up to 250	Up to 250
pressure	Port Y		bar	Static < 10				
Nominal flow $q_{vnom} \pm 10\%$ at Δp =10bar (Δp = valve pressure differential)		L/min	25	-		-	-	
			50	12	5	220	440	
			100	180	0	350	600	
Flow of main valve (max. permissible)		L/min	170	460	0	870	1600	
Pilot oil flow at port X or Y with a step form of input signal from 0 to 100 % (315 bar)		L/min	4.1	8.5		11.7	13	
Pressure fluid				Mineral oil(HL,HLP)to DIN 51 524 Phosphate ester (HFD-R)				
Pressure fluid temperature range		°C	10 to 80, preferably 40 to 50					
Viscosity range		mm²/s	20 to 380, preferably 30 to 45					
Degree of		Maximum permissible degree of contamination of the pressure fluid is to NAS 1638.		A filter with a minimum retention rate of $\beta x = 75$ is recommended				
contamination	Pilot control val	ve	Class 7			x = 5		
Main valve			Class 9			x = 7		
Hysteresis		%	≤ 1					
Response sensitivity		%	≤ 0.5					

Electrical				
Voltage type		DC		
Electrical connection		Plug-in connector to DIN EN175 201-804		
Power, max.		72 (average = 24W)		
Control electronics	•	Integrated into the valve		

Electrical connections, plug-in connector



Contact Signal Α 24 VDC (18 to 35 VDC); $I_{max} = 1, 5 A$; impulse load $\leq 3 A$ Supply voltage Ref. (actual value) C Ref. potential for actual value (contact F) D ± 10 V or 4 - 20mA Differential amplifierinput (command value) Ε 0V ref. potentional Measurement output (act. value) F ± 10 V or 4 - 20 mA PΕ Connected with cooling body and valve housing

Command value:

Referance potential at E and a positive command value at D results in a flow from P to A and B to T. Referance potential at E and a negative command value at D results in a flow from P to B and A to T.

Connection cable:

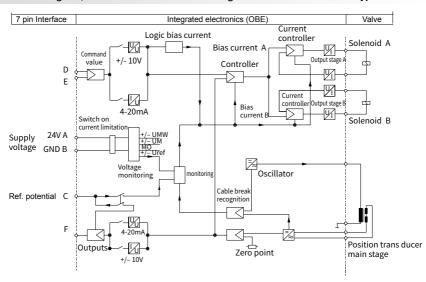
Recommendation: – Up to 25m cable length type LiYCY $7 \times 0.75 \text{ mm}^2$

- Up to 50m cable length type LiYCY 7×1.0 mm External diameter: − 6.5 to

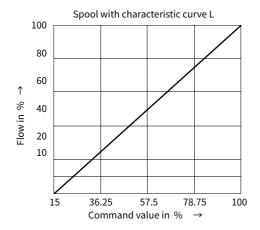
11mm (plastic plug-in connection)

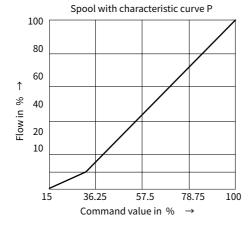
- 8 to 12mm (metal plug-in connector)
 Connect screen to ⊥ only on supply side.

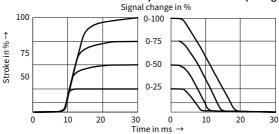
Blockcircuit diagram / connection allocation of the integrated control electronics for type 4WRKE



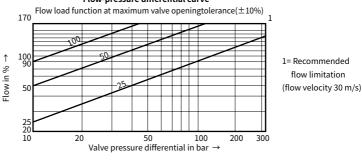
Flow - command value curve





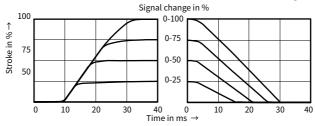


Flow-pressure differential curve

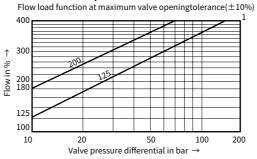


NG 16

Transient function with a step form of electrical input signal

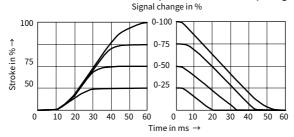


Flow-pressure differential curve



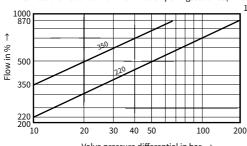
1= Recommended flow limitation (flow velocity 30 m/s) 06

NG 25 Transient function with a step form of electrical input signal



Flow-pressure differential curve

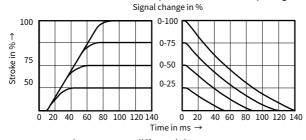
Flow load function at maximum valve openingtolerance(±10%)



1= Recommended flow limitation (flow velocity 30 m/s)

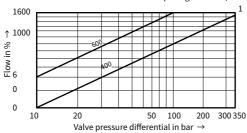
Valve pressure differential in bar →

NG 32 Transient function with a step form of electrical input signal

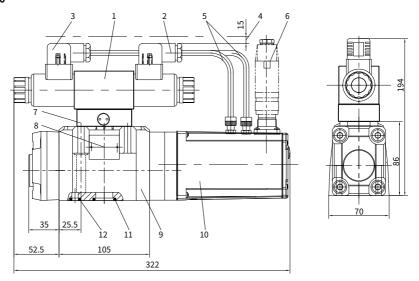


Flow-pressure differential curve

Flow load function at maximum valve opening tolerance ($\pm 10\%$)



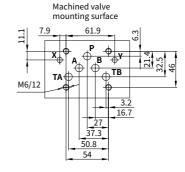
1= Recommended flow limitation (flow velocity 30 m/s)

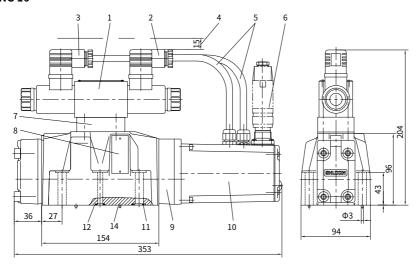


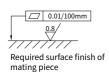


Required surface finish of mating piece

- 1 Pilot control valve
- 2 Plug-in connector "A"
- 3 Plug-in connector "B"
- 4 Space required to remove the plug-in connector
- 5 Cable
- 6 Plug-in connector
- 7 Pressure reducing valve
- 8 Name plate
- 9 Main valve
- 10 Integrated control electronics
- 11 R-ring $13 \times 1.6 \times 2$, ports A, B, P, T
- 12 R-ring 11.18×1.6 ×1.78, ports X and Y







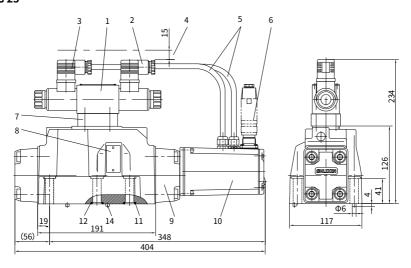
18.3 18.3 18.3 34.1 4×M10 4×M10 4×M10

 $2 \times M6$

101.6

Machined valve mounting surface

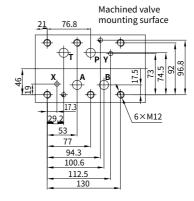
- 1 Pilot control valve
- 2 Plug-in connector "A"
- 3 Plug-in connector "B"
- 4 Space required to remove the plug-in connector
- 5 Cable
- 6 Plug-in connector
- 7 Pressure reducing valve
- 8 Name plate
- 9 Main valve
- 10 Integrated control electronics
- 11 R-ring 22.53×2.3×2.62, ports A, B, P, T
- 12 R-ring 10×2×2, ports X and Y
- 14 Locating pin

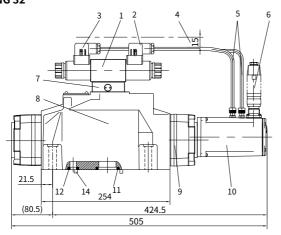


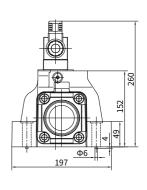


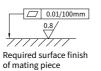
Required surface finish of mating piece

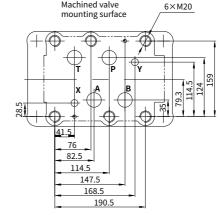
- 1 Pilot control valve
- 2 Plug-in connector "A"
- 3 Plug-in connector "B"
- 4 Space required to remove the plug-in connector
- 5 Cable
- 6 Plug-in connector
- 7 Pressure reducing valve
- 8 Name plate
- 9 Main valve
- 10 Integrated control electronics
- 11 R-ring 27.8×2.6×3, ports A, B, P, T
- 12 R-ring 19×3×3, ports X and Y
- 13 Locating pin











Machined valve

- 1 Pilot control valve
- 2 Plug-in connector "A"
- 3 Plug-in connector "B"
- 4 Space required to remove the plug-in connector
- 5 Cable
- 6 Plug-in connector
- 7 Pressure reducing valve
- 8 Name plate
- 9 Main valve
- 10 Integrated control electronics
- 11 R-ring 42.5×3×3,ports A, B, P, T
- 12 R-ring 19×3×3, ports X and Y
- 13 Locating pin