



# 4WRPEH6...type Servo Valve

4WRPEH6...2XJ...type

Size 6

Max. Working Pressure: 315 bar

Max. Flow: 40 L/min



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#### **Features**

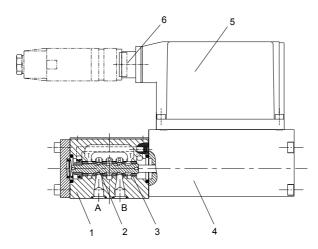
- With control spool and sleeve in servo quality
- Operated on one side, 4/4-fail-safe position in switched off state
- Electric position feedback and integrated electronics(OBE), calibrated in the factory
- Electrical connection 6P+PE signal input differential amplifier with interface"A1":  $\pm 10V$  or interface"F1":  $\pm ...20mA$  ( $R_{sh}$  =  $\pm 200\Omega$ )
- Subplate mounting, porting pattern to ISO 4401-03-02

### **Function and configuration**

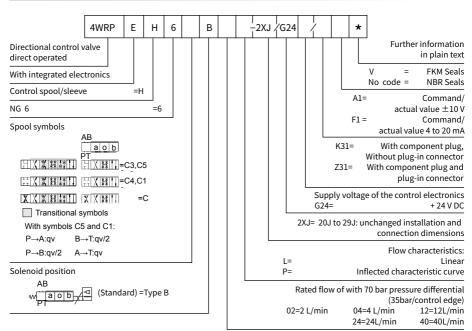
4WRPEH type high-response valve is a pilot-operated directional control valve with electrical position feedback and integrated electronics (OBE). The valves consists of the valve housing(1), spool(2), sleeve(3), control solenoid with position transducer(4) and so on. The specified command value is compared with the actual position value in the integrated electronics (OBE). In the event of a control deviation, the stroke solenoid is activated, which adjusts the control spool against the spring due to the change in the magnetic force.

Lifting/control cross-section is proportionally regulated to the command value. In case of a command value presetting of 0 V, the electronics adjusts the control spool against the spring to central position. In deactivated condition, the spring is untensioned to a maximum and the valve is in fail-safe position. With the electronics switched off, the valve moves immediately into the relevant safe basic position (fail-safe). The switch position P-B/A-T is passed through during this process, which can result in movements on the controlled component. This must be taken into account in system designs.

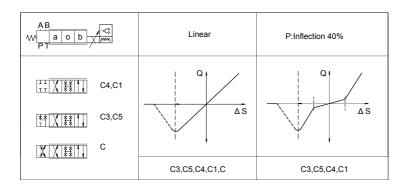
### Type 4WRPEH6...-2XJ/G24...



### **Ordering code**



### **Symbols**

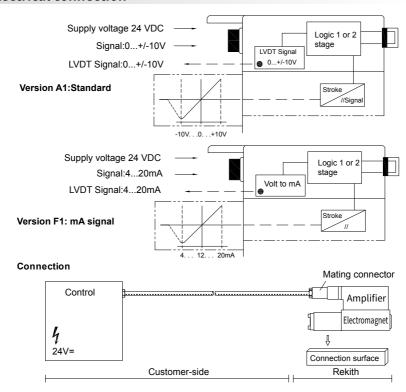


## **Technical data**

General							
Design			Spool valve, direct operated, with steel sleeve				
Actuation			Proportional solenoid with position control, OBE				
Connection type			Subplate mounting, porting pattern according to ISO 4401-03-02-0-05				
Installation position			Any				
Ambient temperature range		°C	-20~+50				
Weight	Veight I		~2.75				
Maximum vibration resistance (test condition)			Max. 25 g, space vibration test in all directions (24h)				
Hydraulic (measure	d at p=100bar, with HI	P46 at $\vartheta_{\rm oil}$ =	40°C ±5°C	:)			
pressure fluid			Mineral oil (HL, HLP)to DIN 51 524				
Viscosity range	Recommended	mm²/s	20…100				
	Maximum admissible	mm²/s	10…800				
Hydraulic fluid temperature range		°C	-20 to +70				
Maximum admissible degree of contamination of the hydraulic fluid, cleanliness class according to ISO 4406 (c)			Class 18/16/13				
Rated flow (Δp = 35 bar per edge)		L/min	2	4	12	24	40
Maximum operating pressure		bar	Port A, B, P: 315				
Maximum operating pressure bar		Port T: 250					
Leakage flow at 100 bar	Linear	cm³/min	< 150	< 180	< 300	< 500	< 900
	Nonlinear	cm³/min	_	_	-	< 300	< 450
Static/Dynamic							
Hysteresis		%	≤ 0.2				
Actuating time for signal step 0 100%		ms	10				
Temperature drift			Zero shift < 1% at ΔT=40°C				
Zero compensation	Zero compensation			Ex factory ±1%			

Electric, control electronics integrated in the valve					
Relative duty cycle		100ED			
Protection class according to EN 6052	29	IP 65.			
Connection		Plug-in connector 6P+PE, DIN 43563			
Supply voltage		24VDC <sub>nom</sub>			
Terminal A		min. 21VDC / max. 40VDC			
Terminal B		0V (ripple max. 2)			
Fuse protection, external	AF	2.5			
Input, version "A1"		Differential amplifier, Ri = 100 kΩ			
Terminal D (U <sub>E</sub> )		0±10V			
Terminal E		OV			
Input, version "F1"		Load, $R_{sh} = 200 \Omega$			
Terminal D (I <sub>D-E</sub> )		41220mA			
Terminal E (I <sub>D-E</sub> )		Current loop I <sub>D-E</sub> return			
Test signal, version "A1"		LVDT			
Terminal F (U <sub>Test</sub> )		0±10V			
Terminal C		Reference 0 V			
Tt-i		LVDT signal 4 (12) 20 mA on external load			
Test signal, version "F1" Terminal F ( I F.C )		200 500 Ωmaximum			
Terminal C ( I <sub>E-C</sub> )		4 (12) 20mA (output)			
		Current loop I <sub>F-C</sub> return			
Adjustment		calibrated before delivery, see characteristic curves			

### **Electrical connection**



### Technical data for the cable

Version: - Multi-core wire

- Litz wire structure, extra fine wire according to VDE 0295, class 6

- Protective earthing conductor, green-yellow

- Cu shielding braid

Number - Determined by the valve type,

of wires: connector type and signal configuration

Line Ø: -0.75 mm² to 20 m of length 1.0 mm² to 40 m of length OuterØ: -

9.4...11.8 mm

12.7...13.5 mm

#### Note:

Supply voltage 24 V DC<sub>nom</sub>

if the value falls below 18V = an internal fast switch-off is effected which can be compared with "Release OFF".

Additionally for version F1:

 $I_{D-E} \geqslant 3mA$  - valve is active

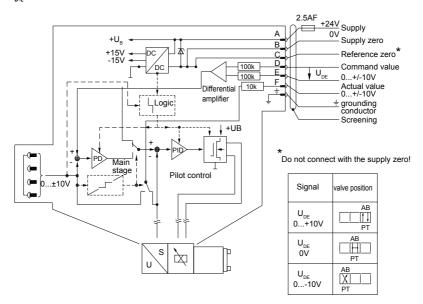
 $I_{D-E} \leq 2mA$  - valve is deactivated.

Electric signals taken out via control electronics may not Abe used for the switch-off of safety-relevant machine functions!

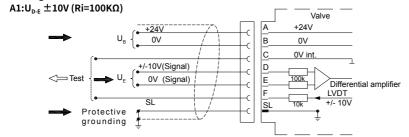
### Integrated electronics (OBE)

### Block diagram/pin assignment

A1:U<sub>D-E</sub> 0...±10V



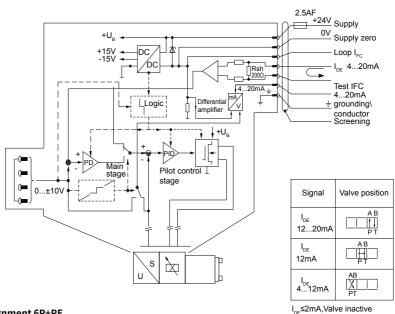
### In assignment 6P+PE



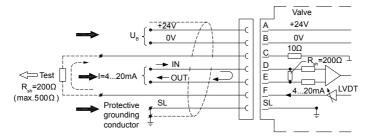
### **Integrated electronics (OBE)**

### Block diagram/pin assignment

F1: I<sub>D-E</sub> 4...20mA



In assignment 6P+PE F1: I<sub>D-E</sub> 4...20mA (Rsh =200 Ω)

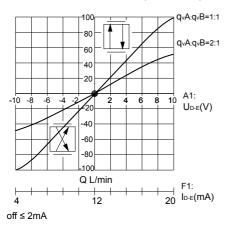


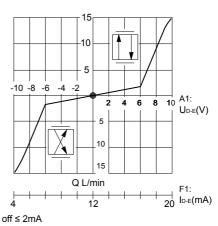
**Characteristic curves** (measured at p = 100bar, with HLP46,  $\vartheta_{oil}$  = 40°C  $\pm$ 5°C)

Flow-signal function

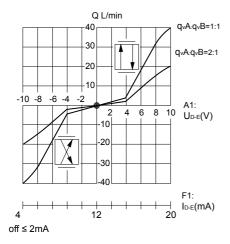
 $q_v = f(U_{D-E}), q_v = f(I_{D-E})$ 

### Linear characteristic curve (version "L")

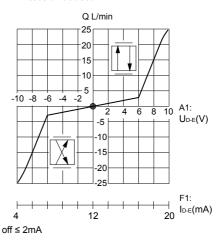




Inflected characteristic curve"P", inflection at 40%

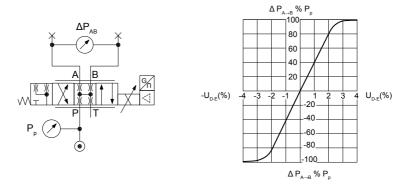


Inflected characteristic curve "P", inflection at 60%

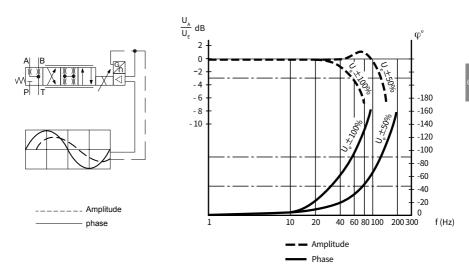


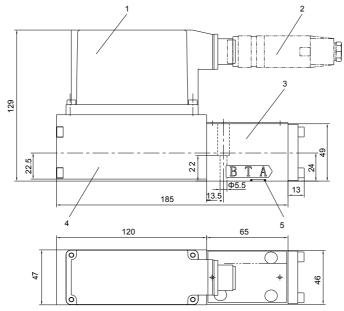
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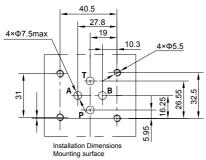
### **Characteristic curves:** Pressure amplification (measured at p =100bar, with HLP46, $\vartheta_{oil}$ =40°C $\pm 5$ °C)



### **Characteristic curves:** Bode diagram (measured at p =100bar, with HLP46, ϑ₀ii t=40°C ±5°C)







- 1 Integrated electronics (OBE)
- 2 Mating connectors
- 3 Valve housing
- 4 Control solenoid with position transducer
- 5 O-ring 9.25×1.78 (for ports P, A, B, T)

